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A NOTE ON FOLYNOMIAL MATRIX FUNCTIONS OVER A FINITE FIELD. (U)
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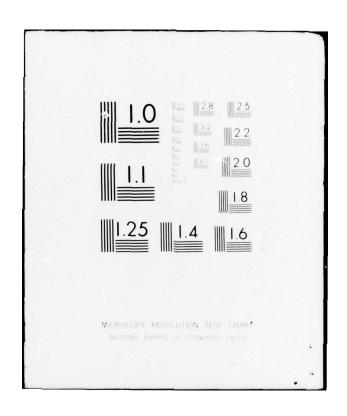


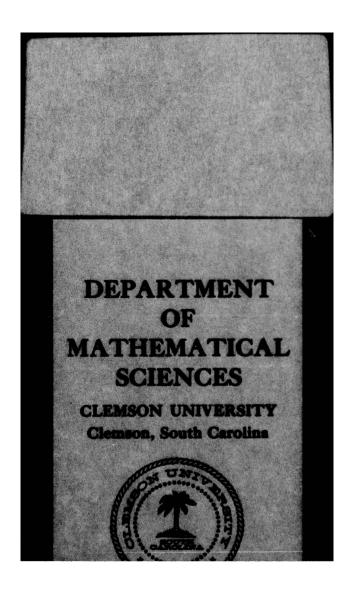






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A NOTE ON POLYNOMIAL MATRIX FUNCTIONS OVER A FINITE FIELD

BY

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DEPARTMENT OF MATHEMATICAL SCIENCES CLEMSON UNIVERSITY

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A Note on Polynomial Matrix Functions over a Finite Field by J.V. Brawley*

1. Let F = GF(q) denote the finite field of order q, and let $F_n \ \ \text{denote the ring of nxn matrices over F.} \ \ \text{Consider an element}$ $A(x) \ \epsilon \ F_n[x]; \ i.e.,$

(1)
$$A(x) = A_N x^N + A_{N-1} x^{N-1} + \dots A_1 x + A_0$$

where ${\bf A}_i \ \epsilon \ {\bf F}_n$. This polynomial defines via substitution several functions from ${\bf F}_n$ to ${\bf F}_n$. Two such functions are

(2)
$$B \rightarrow A_r(B) = A_N B^N + A_{N-1} B^{N-1} + ... + A_1 B + A_0$$

and

(3)
$$B \to A_L(B) = B^N A_N + B^{N-1} A_{N-1} + ... + BA_1 + A_0$$
.

We call (2) and (3), respectively, the right and left polynomial functions determined by A(x) with the terms right and left indicating the side on which the substituting variable is placed.

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Definition. A function A: $F_n \to F_n$ is called a <u>right</u> respectively <u>left</u>) <u>polynomial function</u> if there exists a polynomial A(x) ε $F_n[x]$ which represents A via the right substitution (2) (respectively(3)).

In this note we obtain unique representations for and determine the number of right (left) polynomial functions $A\colon F_n \to F_n.$ Proofs will be given for the right functions which can be obviously modified for the left polynomial functions.

2. Recall that

$$L_{\mathbf{n}}(\mathbf{x}) = \prod_{i=1}^{\mathbf{n}} (\mathbf{x}^{q^{i}} - \mathbf{x})$$

is the monic polynomial of least degree in F[x] satisfied by every B ϵ F_n ; indeed, $L_n(x)$ is the least common multiple of all degree n polynomials in F[x] [See, 2]. We define δ by

(5)
$$\delta = \deg L_n(x) = q^n + q^{n-1} + ... + q.$$

THEOREM 1. Let $Z(x) = \sum_{i=0}^{N} Z_i x^i$ be a polynomial in $F_n[x]$ with $degZ(x) = N < \delta$. If $Z_r(B) = Z_N B^N + \ldots + Z_1 B + Z_0 = 0$ for every $B \in F_n$, then $Z_i = 0$, $i = 0, 1, 2, \ldots, N$.

Proof. Let $f(x) = x^n - a_{n-1} x^{n-1} - \dots - a_1 x - a_0$ be an arbitrary polynomial of degree n in F[x], and let $C \in F_n$ denote the companion matrix of f(x). Dividing Z(x) by f(x) we obtain

(6)
$$Z(x) = Q(x) f(x) + R(x)$$

where Q(x) and R(x) are in $F_n[x]$ with

(7)
$$R(x) = R_{n-1}x^{n-1} + \ldots + R_1x + R_0.$$

Since f(x) is a scalar polynomial we may substitute an arbitrary matrix B into (6) to get $Z_r(B) = Q_r(B)f(B) + R_r(B)$. In particular, for every nonsingular P ϵ GL(n,q) it follows from the Hamilton-Cayley theorem that

$$0 = Z_r(PCP^{-1}) = R_r(PCP^{-1})$$
.

Thus $(R_r(PCP^{-1}))P = 0$ or

(8)
$$R_{n-1}PC^{n-1} + R_{n-2}PC^{n-1} + \dots + R_1PC + R_0P = 0$$

for every $P \in GL(n,q)$.

Now it is known [1] that each matrix X ϵ F can be written as a linear combination of nonsingular matrices P; i.e.,

$$X = c_1 P_1 + c_2 P_2 + ... + c_t P_t$$
, $c_i \in F$.

If follows from (8) that

(9)
$$R_{n-1}XC^{n-1} + R_{n-2}XC^{n-1} + \dots + R_1XC + R_0X = 0$$

for every $X \in F_n$. In particular, if we take $X = E_m$ where E_m has a 1 in position (m,1) and zeros elsewhere we find through actual computation that equation (9) reduces to

where $R_k = (r_{ij}^{(k)})$. Thus column m of R_k is zero for k = 0, 1, ..., n-1 and m = 1, 2, ..., n; i.e., $R_k = 0$ for k = 0, 1, ..., n-1. It follows from (6) that f(x) divides Z(x) for every monic of degree n; hence $L_n(x)$ divides Z(x). But deg $Z(x) < \deg L_n(x)$ so Z(x) must be the zero polynomial; i.e., every $Z_i = 0$ and the proof is complete.

As a corollary to Thec we have the following:

THEOREM 2. Each right polynomial function $A:F_n \to F_n$ can be represented uniquely by a polynomial $A(x) \in F_n[x]$ of degree $< \delta$ and each such polynomial represents a right polynomial function. The number of right polynomial functions is therefore $q^{n^2\delta}$.

Proof. If $A_1(x)$ and $A_2(x)$ have degree $< \delta$ and each represent the right polynomial function A then $A_1(x) - A_2(x)$ represents the zero function; hence by Theorem 1, $A_1(x) = A_2(x)$.

Finally let A be a right polynomial function and let A(x)

represent A. By division

$$A(x) = Q(x)L_n(x) + R(x)$$

where R(x) has degree < δ . Clearly, R(x) represents A.

References

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- J. V. Brawley, L. Carlitz, and Jack Levine. Scalar polynomial functions on the n×n matrices over a finite field. Linear Algebra and Its Applications. 10(1975), 199-217.

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Let F = GF(q) denote the finite field of order q, and let F_n denote the ring of $n \times n$ matrices over F. Each matrix polynomial $A(x) = A_n x^N + \ldots + A_1 x + A_0$ in $F_n[x]$ defines via substitution several

 $A(x) = A_N x^N + ... + A_1 x + A_0$ in $F_n[x]$ defines via substitution several functions from F_n to F_n . Two such functions, called respectively, the right and left polynomial functions determined by A(x) are

$$B + A_r(B) = A_N B^N + \dots + A_1 B + A_0$$

 $B + A_L(B) = B^N A_N + \dots + BA_1 + A_0$

A function $A:F_n \to F_n$ is called a right (left) polynomial function if there exists $A(x) \in F_n[x]$ which represents A via the right (left) substitution $B \to A_r(B)$ $(B \to A_L(B))$. This paper obtains a unique representation for and determines the number of right (left) polynomial functions $A:F_n \to F_n$.

